

First-Order Linear DEForm:  $y'(x) + p(x)y(x) = q(x)$ Integrating factor:  $I(x) = e^{\int p(x) dx}$ Bernoulli EquationsForm:  $y' + p(x)y = q(x)y^n$ Strategy: Divide through by  $y^n$ , multiply by  $1-n$  then use the integrating factor:

$$I(x) = e^{\int (1-n)p(x) dx}$$

Homogeneous DEForm:  $\frac{dy}{dx} = f(x, y)$ , where  $f(tx, ty) = f(x, y)$ Strategy: Let  $y = ux$ , DE becomes separableExact DEThe DE  $F_x(x, y) dx + F_y(x, y) dy = 0$  is exact if  $F_{xy}(x, y) = F_{yx}(x, y)$ .The solution is  $F(x, y) = C$ Integrating FactorIf  $M(x, y) dx + N(x, y) dy = 0$  is not exact:a) If  $p(x) = \frac{M_y - N_x}{N}$  is independent of  $y$ , use the integrating factor:  $\mu(x) = e^{\int p(x) dx}$ b) If  $q(y) = \frac{N_x - M_y}{M}$  is independent of  $x$ , use the integrating factor:  $\mu(y) = e^{\int q(y) dy}$ Euler's MethodGiven  $y' = f(x, y)$   $y(x_0) = y_0$ 

$$y_{i+1} = y_i + hf(x_i, y_i)$$

1st and 2nd-Order Circuits

$$\frac{di}{dt} + \frac{R}{L}i + \frac{1}{LC}q = \frac{1}{L}E(t)$$

where  $i(t) = \frac{dq}{dt}$ Mixing Problems

$$W'(t) = R_1 - R_2$$

$$Q'(t) = C_1R_1 - \frac{Q}{W(t)}R_2$$

Variation of ParametersForm:  $y'' + a(x)y' + b(x)y = F(x)$ , with solutions to the homogeneous case:  $y_1$  and  $y_2$ 

$$y_p = y_1 \int \frac{-y_2 F(x)}{W(y_1, y_2)} dx + y_2 \int \frac{y_1 F(x)}{W(y_1, y_2)} dx$$

Spring Problems

$$my''(t) + cy'(t) + ky(t) = F(t)$$

where  $m$  is the mass of the weight,  $c$  is the damping constant,  $k$  is the spring constant, and  $F$  is an external force.Cauchy-Euler EquationsForm:  $ax^2y'' + bxy' + cy = 0$ Let  $x = e^u$  which leads to

$$ar(r-1) + br + c = 0$$

and  $y(u) = e^{ru}$ , substitute back to find  $y(x)$ Method of Frobenius For  $x^2y'' + xp(x)y' + q(x)y = 0$ ,  $r_1$  and  $r_2$  are the real roots of the indicial equation:  $r(r-1) + p_0r + q_0 = 0$ 1. If  $r_1 - r_2$  is not an integer,

$$y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1} \quad \text{and} \quad y_2 = \sum_{n=0}^{\infty} b_n x^{n+r_2}$$

2. If  $r_1 - r_2$  is a positive integer,

$$y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1} \quad \text{and} \quad y_2 = Ay_1 \ln(x) + \sum_{n=0}^{\infty} b_n x^{n+r_2}$$

where  $A$  is a constant and may turn out to be zero.3. If  $r_1 = r_2 = r$ ,

$$y_1 = \sum_{n=0}^{\infty} a_n x^{n+r} \quad \text{and} \quad y_2 = y_1 \ln(x) + \sum_{n=0}^{\infty} b_n x^{n+r}$$

Common Laplace Transforms

$$\mathcal{L}[t^n] = \frac{n!}{s^{n+1}}$$

$$\mathcal{L}[e^{at}] = \frac{1}{s-a}$$

$$\mathcal{L}[\sin bt] = \frac{b}{s^2 + b^2}$$

$$\mathcal{L}[\cos bt] = \frac{s}{s^2 + b^2}$$

$$\mathcal{L}[\sinh bt] = \frac{b}{s^2 - b^2}$$

$$\mathcal{L}[\cosh bt] = \frac{s}{s^2 - b^2}$$

$$\mathcal{L}[\delta(t-a)] = e^{-as}$$

Laplace Transform of Derivatives

$$\begin{aligned}\mathcal{L}[y^{(n)}] &= s^n \mathcal{L}[y] - s^{n-1}y(0) - s^{n-2}y'(0) - \dots \\ &\dots - sy^{(n-2)}(0) - y^{(n-1)}(0)\end{aligned}$$

The First Shifting Theorem

If  $\mathcal{L}[f(t)] = F(s)$  then

$$\mathcal{L}[e^{at}f(t)] = F(s-a)$$

The Second Shifting Theorem

If  $\mathcal{L}[f(t)] = F(s)$  then

$$\mathcal{L}[u(t-a)f(t-a)] = e^{-as}F(s)$$

Convolution Product

$$(f * g)(t) = \int_0^t f(t-\tau)g(\tau) d\tau$$